

Augmented Reality

Part 1 – Technologies & Applications

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Betreuer:

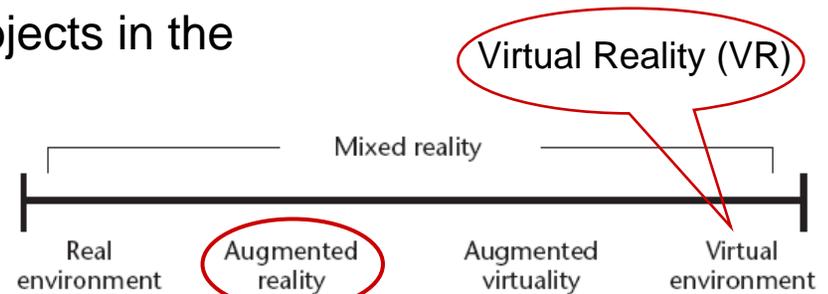
Marc Langheinrich

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Definition

Augmented Reality (AR):

- Supplementation of the **real** world with **virtual** objects
- **Coexistence** of real and virtual objects in the *same* real space
- Relatively new research field (~1993)



Milgram's reality-virtuality continuum (1994)

3 characteristics of AR-Systems:

1. **Combines** real and virtual objects in a real (3-D) environment
2. Runs **interactively** and in **real time**
3. Registers (**aligns**) real and virtual objects with each other



Ronald T. Azuma

Augmentation

- Adding virtual objects to the real world
- Removing or hiding objects from the real world (*mediated / diminished reality*)

- **Output** of an AR-System:

- might apply to *all* human senses (ability not only to see but also to *hear, touch* and *smell* the virtual world)

- **Input** of an AR-System:

- everything a **sensor** can detect (also *ultrasound, infrared, ultraviolet* frequencies)

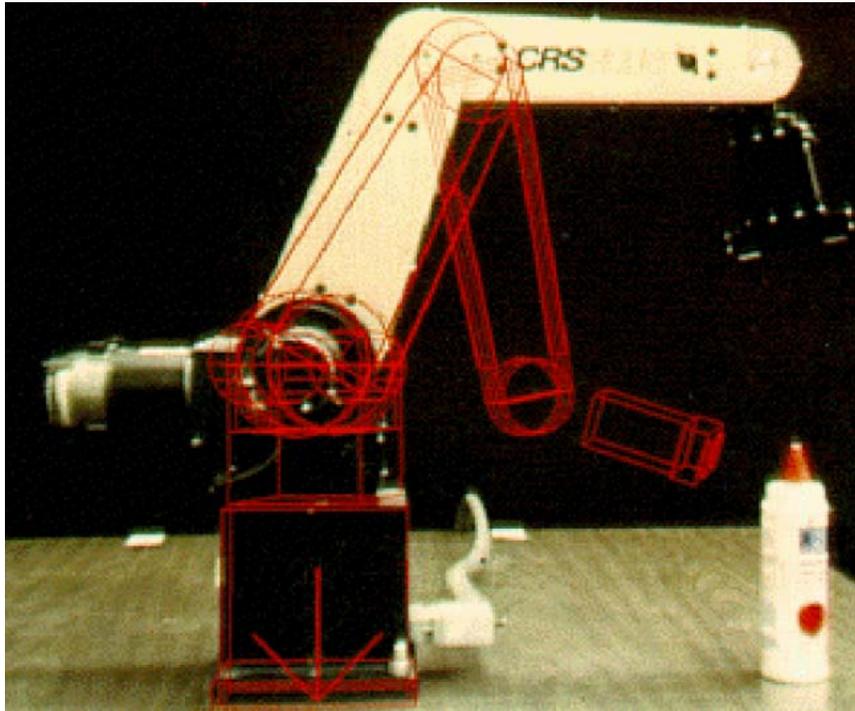
- Not a trivial task!

- Identify *what* information should be provided
- Appropriate **representation** of that data
- **User interaction** with the AR-System

Why is AR useful?

- AR enhances *user interactions* with the real world
 - Intelligence Amplification (IA)
 - „using the computer as a tool to make a task easier for human to perform“ [Brooks96]
- Virtual objects can make information not directly detectable by **human senses** visible
 - this information helps a user perform real-world tasks

Example 1 – Robot path planning

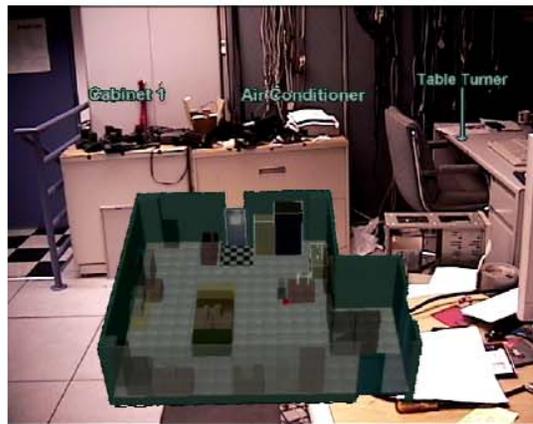


[Drascic93 and Milgram93]

- control a *virtual version* of the robot
- plan the robot's actions on the virtual counterpart in **real time**
- test & determine the plan
- virtual overlay **predicts** the effects of the manipulation
- real robot executes the specified plan

Example 2

Annotated Situation-Awareness Aid



[B.Bell, T.Höllerer, S.Feiner – CS Dep. Columbia University 2002]

- Overlaid graphics annotate the surrounding world
 - label objects
 - detailed information about the objects
- Aid is based on a **world in miniature** (WIM)
- Controlling the *position*, *scale* and *orientation* of the WIM only through **head orientation**
 - > *hands-free interface*
- Looking down to access the aid

Application Domains

1. Medical visualization
 - e.g. Visualization and training aid for surgery
2. Manufacturing and repair
 - e.g. Superimposed 3-D (animated) drawings instead of numerous complicated manuals
3. Annotation and visualization
 - e.g. show where the pipes and electric lines are inside the walls
4. Robot path planning
 - *example on slide 5*
5. Entertainment
 - e.g. in sports broadcasting (*real time* annotations on race cars)
6. Military aircraft navigation and targeting
 - e.g. aim the aircraft's weapons by looking at the target

Overview

1. Introduction

- *Definition AR*
- *Augmentation*
- *Why is AR useful?*
- *Examples & Application Domains*

→ 2. Design of AR-Systems

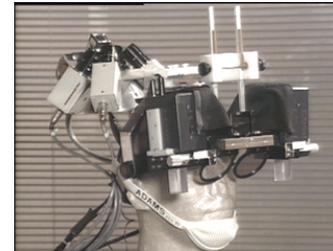
- *Display Types & Technologies*
- *Advantages*
- *AR vs. Virtual Reality*

Design of AR-Systems

Types of displays used in AR:

1. Head-Mounted-Displays (HMD)

- LCD-based, head-worn
- virtual retinal displays



2. Handheld displays

- flat panel LCD displays with an attached camera



3. Projection displays

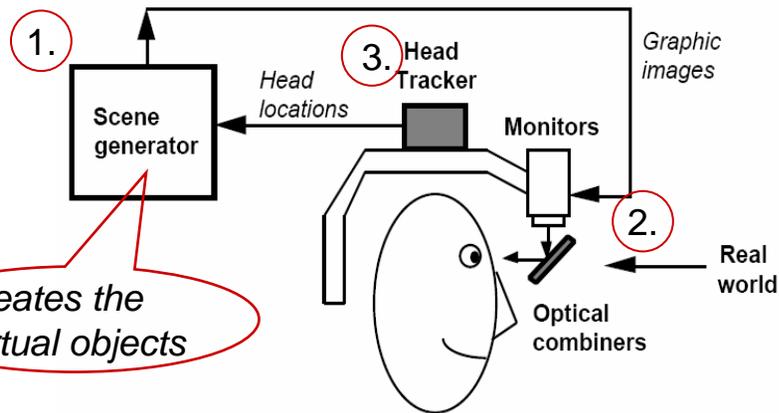
- project the virtual information *directly* on the physical objects
- **head-worn** or **fixed** projector in the room
- objects with *special surface reflecting* the light
- projected images only visible along the *line of projection*



Design of AR-Systems (2)

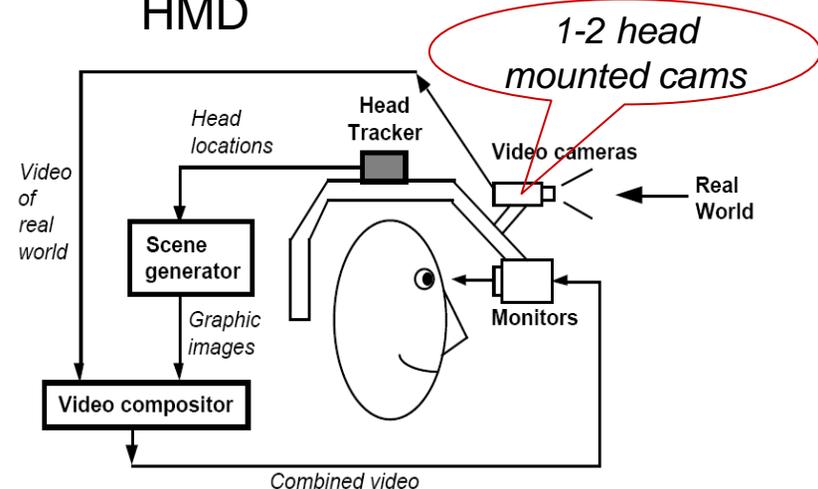
Optical technologies:

- e.g. an optical **see-through** HMD



Video technologies:

- e.g. a video **see-through** HMD



3 basic subsystems:

1. *Scene generator*
2. *Display device*
3. *Tracking and Sensing*



Design of AR-Systems (3)

■ Optical:

- + optical **blending** simpler
- + **safety** (power failure)
- + no reduction of **resolution**
(of the real world)
- + no **eye offset**

■ Video based:

- + easier to match the **brightness**
- + **wide field-of-view** displays are easier to build
- + real and virtual view **delays** can be matched

AR vs. Virtual Reality (VR)

- Rendering is easier! (in AR)

- VR-Systems completely *replace* the real world
- AR-Systems „only“ *supplement* the real world
- only few applications require **photorealism**
 - text and 3-D wireframe drawings might suffice

- Monitor resolution less crucial! (in AR)

- no reduction of resolution (of the real environment)
 - smaller field-of-view acceptable
- } optical HMDs

⇒ Lower requirements in AR than VR?

- **Tracking** and **sensing** much more crucial (in AR)

- **Registration Problem** in AR -> limits the applications of AR

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→ 3. Registration Problem

- *Definition*
- *Dynamic Errors & System Delays*
- *Wider use of AR?*

Registration Problem

Definition:

AR-Registration: Proper alignment of real objects and virtual objects
(-> *perfect illusion that the two worlds coexist*)

- **Accurate** registration required for many applications
 - e.g. in *medical visualization*

- Accurate registration requires:
 1. Accurate **tracking** of the user's head (viewpoint)
 2. **Sensing** the locations of the other objects in the environment

- Registration errors result in *visual-visual conflicts*
 - easy detectable -> very high resolution of the human eye!

Registration Problem (2)

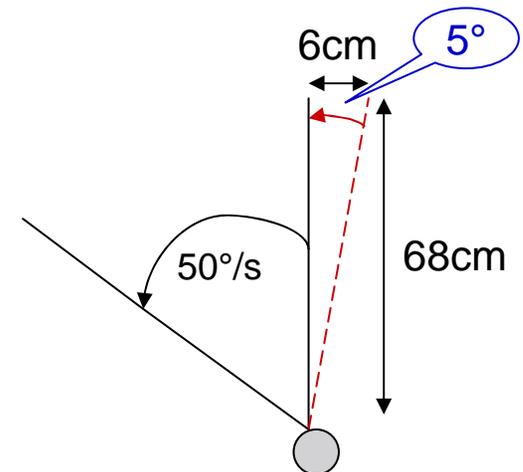
- AR is an **interactive** medium
 - User looks where he wants, the system must respond within milliseconds
 - **Dynamic errors** occur when the *viewpoint* or the real objects begin moving
 - Dynamic errors are the *largest* contributors to *registration errors*
- Main source for dynamic errors:
 - **System delays**

Registration Problem (3)

- End-to-end system delay (~100 ms)
 - Seriously hurt the **illusion** that the real and virtual worlds coexist!
 - Only problematic when motion occurs
 - **Angular accuracy** of a small fraction of a degree required!

- **Example:**

- user wearing a see-through HMD
- given a system lag of 100 ms
- head rotation of $50^\circ/\text{s}$
- -> angular dynamic error of 5°
- -> 6 cm (at an arm length of 68 cm)



Reducing dynamic errors

1. Reduce / eliminate system delays
 - minimize scene generator latency
2. Reduce apparent lag
 - use feed-forward techniques
 - e.g. render a much larger image than needed
3. Match temporal streams
 - only in video based AR-Systems
 - delay the *video stream* from the real world
4. Prediction
 - predict the future viewpoint and object locations

Obstacles in a wider use of AR

- Technological limitations
 - more **accurate**, **lighter**, **cheaper** and **less power consuming** displays, trackers and sensors
- User interface limitations
 - suitable UIs
- Social acceptance
 - Fashion?
 - **Privacy**

Questions

- Questions?

- References:

- Ronald T. Azuma: “*A survey of augmented reality*”
Presence: Teleoperators and Virtual Environments, Vol. 6, No. 4, pp. 355-385, August 1997
- R. Azuma, Y. Baillet, R. Behringer, S. Feiner, S. Julier, B. MacIntyre:
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UIST '02: Proceedings of the 15th annual ACM symposium on User interface software and technology, ACM Press, ISBN 1-58113-488-6, pp. 213-216, 2002